

SBD Automotive

The Software Defined Vehicle and OSS

OSS as an emerging key enabler to build SDV

AGL members F2F meeting

October 19, 2022







SBD Automotive Mission

Delivering confidence through clarity, insight and vision

Our Areas of Expertise











Shared

Electric

Secure

We are experiencing a life-changing mobility paradigm shift

Consumer

Technology



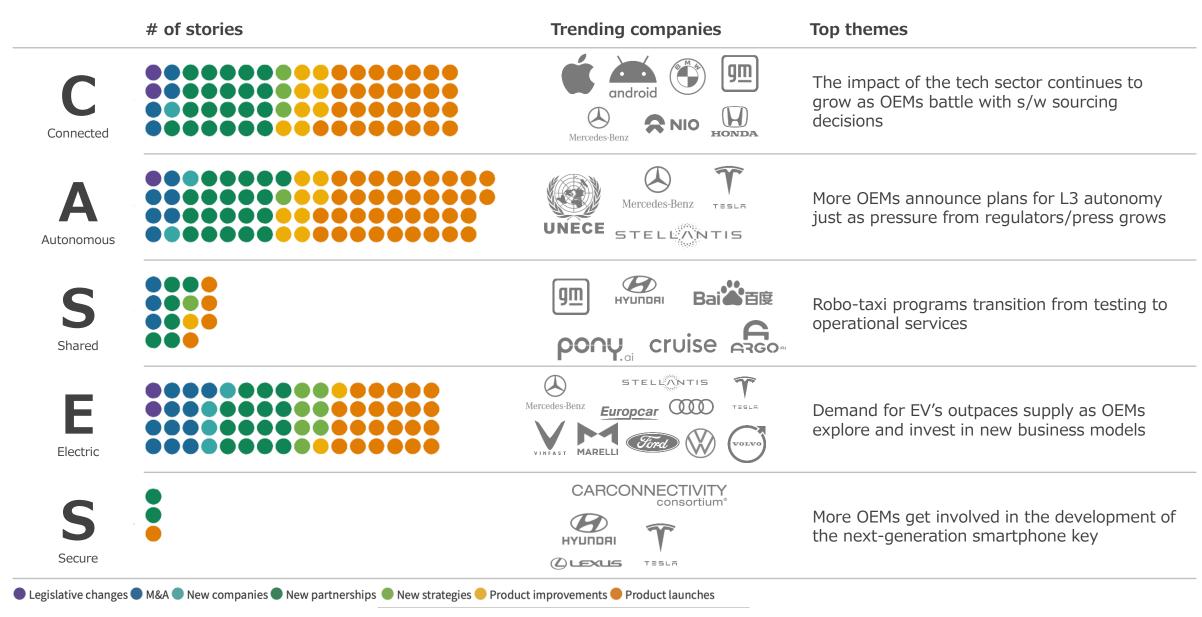
	trends	habits	regulations	eco-system	
	SensorsConnectivityComputing	 Urbanization Digitization Mobility	PrivacySecurityEnvironmental	 Tech giants Start-ups Suppliers	
Traditional paradigm					New paradigm
Buy it					Use it
Drive it					Be driven
Fill it up					Charge it
Get there					Enjoy the ride

New

Evolving

With heavy investment in connectivity, autonomy, and EVs





Software Defined Vehicles

What's driving car makers forward?

Increase

- Speed-to-market
- Aftersales revenue
- Customer satisfaction
 - Brand loyalty

Decrease

- Bill of materials
- Recall rate
- Depreciation
- Vulnerabilities

The software-defined automaker's hierarchy of needs



- Commercialization
- Customer Experience
- Organization & Development Process
- Software-Defined Vehicle & Car-to-Cloud
- E/E and Vehicle Platform





FOCUS LOCAL MARCIALIZATION CUSTOMER Experience

- 3 Organization & Development Process
- 2 Software-Defined Vehicle & Car-to-Cloud
- E/E and Vehicle Platform





What is Software Defined Vehicle?

Defining the software-defined vehicle





SDVs allow software to be **designed**, **developed and tested in a fully virtualized environment**, leveraging the scale of cloud services to simulate vehicle software



SDVs require multiple layers of hardware and software across different domains in order to implement this separation



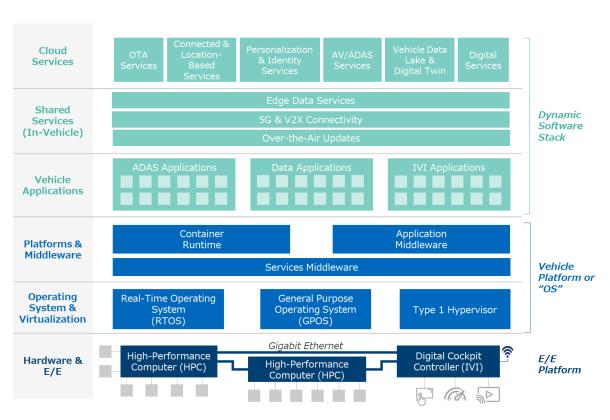
SDVs allow OEMs to dynamically implement new business models & customer experiences much faster than before



SDVs create **significant disruption** in the traditional automotive electronics supply chain while creating **new "blue oceans"**



Much of the core SDV software stack is nondifferentiating, making **standards & opensource software** attractive to OEMs



Source: SBD Automotive // The Software-Defined Vehicle (2021)

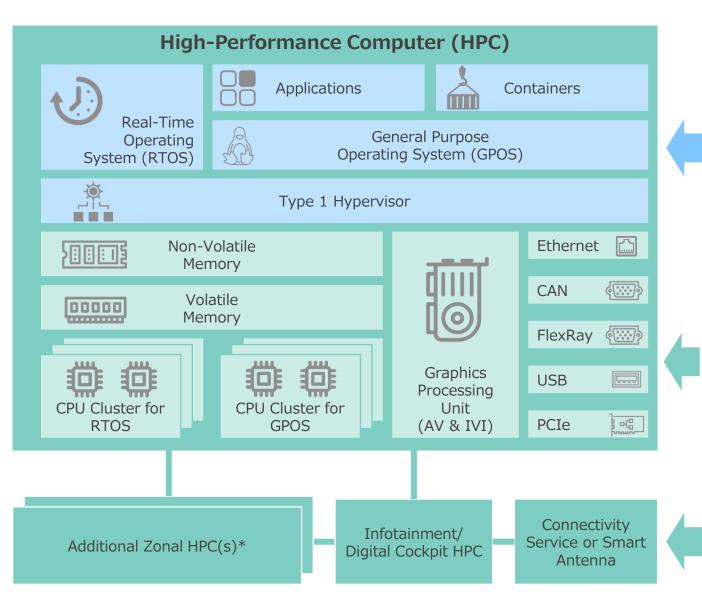
Vehicle 4.0: The evolution of the software-defined vehicle



<u>Definition</u>			<u>Characteristics</u>		Technologies/Enablers
		No over-the-air updates		Microcontroller ECUs	
Vehicle 1.0	Vehicle 1.0 Features developed & implemented in conjunction with underlying hardware Functional	₽	Tightly coupled ECUs		Real-time operating systems
Functional		© <u></u> 8	Basic infotainment services	+++	CAN-based architecture
		CA.	Embedded or brought-in infotainment applications	(i)	Embedded 4G connectivity
Vehicle 2.0	Enhanced infotainment domain with apps, connectivity, and limited updateability	8	Limited software updates for infotainment		Cloud platform for content, services
Digital		ŤÅ	Limited driver personalization		Driver identity provider
	Core domains (ADAS, digital		Regular software updates for core functional domains	Œ	Ethernet E/E backbone
Vehicle 3.0	cockpit, connectivity) implement abstracted software runtime & middleware	~ O	Dynamic HMI for vehicle functions (voice, multiple screens, etc.)		Domain-based middleware
Updateable	middleware	₹ Ţ	OEM and/or 3 rd party software applications		OEM-managed software development
Vehicle 4.0	Computing workloads can be		Redundant application processing across domains/zones		5G connectivity
	dynamically shifted between vehicle computers & offboard		Continuous software delivery	2	mbedded 4G connectivity loud platform for content, ervices river identity provider thernet E/E backbone comain-based middleware EM-managed software evelopment G connectivity dge application runtime (i.e. dge containers) omogenous computing platform
Software-Defined	infrastructure		Dynamic data processing between vehicle, edge, & cloud	*	Homogenous computing platform between vehicle & cloud

High Performance Computer is a foundation for H/W abstraction





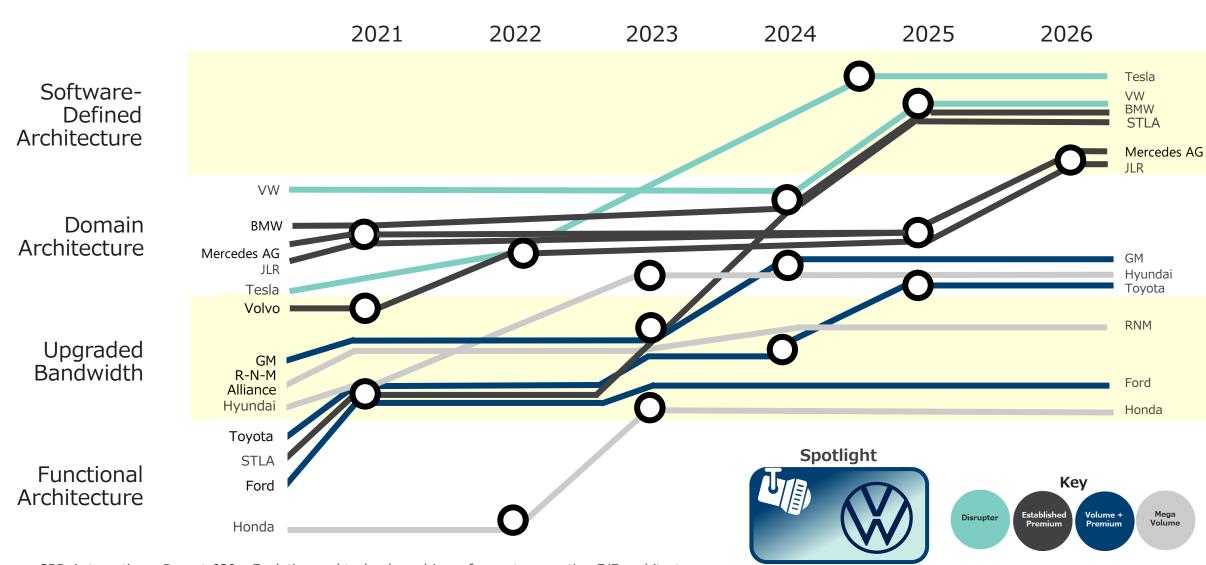
- Applications & containers leverage services on the GPOS
- Simultaneous execution of real-time and general purpose operating systems using CPU clusters
- Type 1 hypervisor provides hardwareoptimized virtualization services
- HPCs provide a variety of physical interfaces
- GPUs power the processing of camera & radar data for ADAS/AV, and rendering for digital cockpit interfaces.
- CPU clusters ensure redundant processing for both RTOS and GPOS applications
- Multiple HPCs to provide high availability, optimized, redundant AV services and digital cockpit application

SDV needs overhaul in EE architecture as well as S/W structure





Vehicle platform engineering projects will take many years to reach maturity, scale within car parc

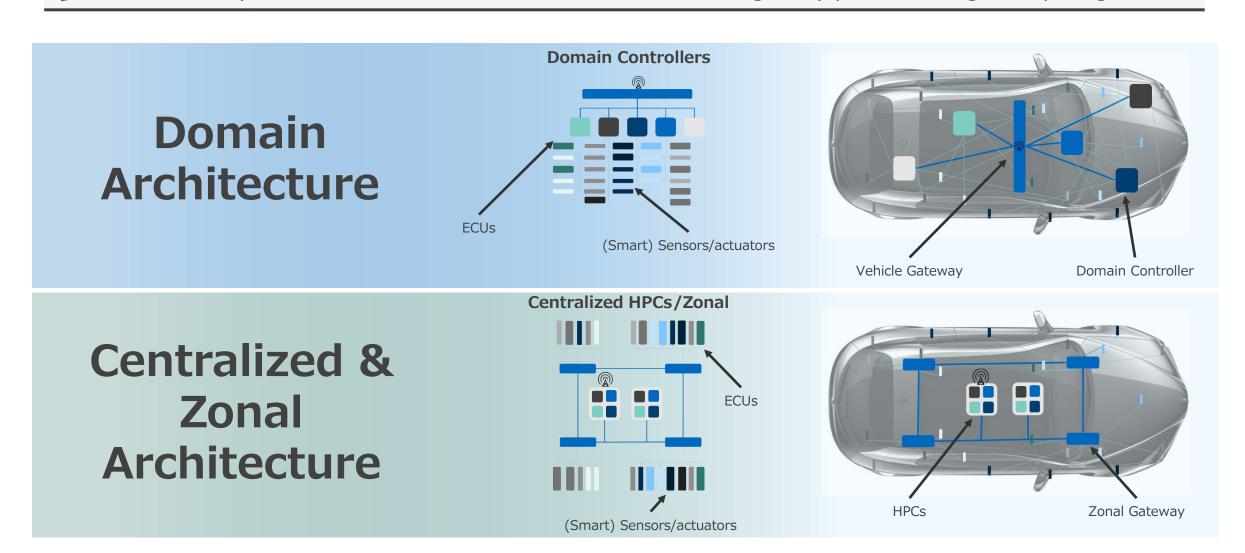


SDV will be achieved on a centralized zonal EE architecture





SoC scalability will drive consolidation and abstraction, enabling entry points for edge computing



Source: SBD Automotive - Report 213 - Advanced Computing

Personalized, automated vehicles rely on cloud, edge



On Premise



New commercialization opportunities require new car-to-cloud platform services to meet OEM needs

Far & In-Vehicle Embedded Edge



- Intelligent sensors
- Independent modules
- Containers
- Cloud-native apps
- Running in-vehicle via HPC

Network Edge



- Containers
- Cloud-native apps
- Running in network infrastructure

Containers or virtual machines

Cloud

- (Usually) shared data center
- Supporting regional and global workloads

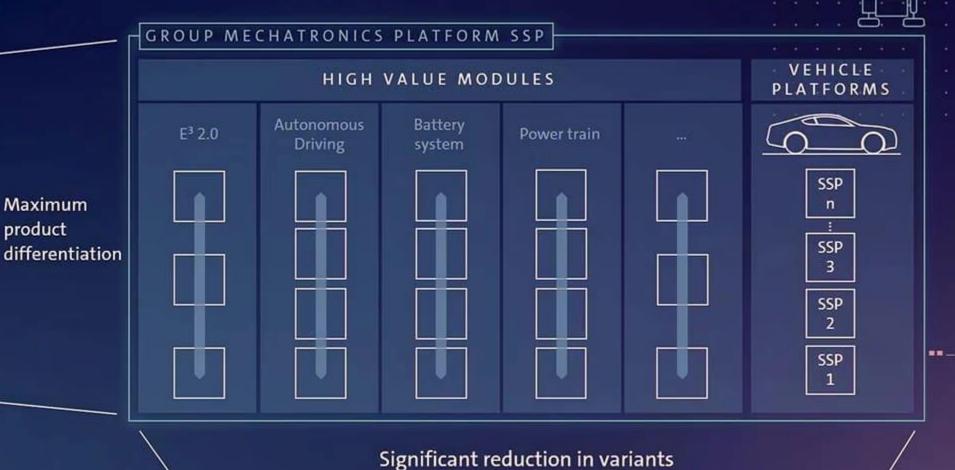
- Centralized
- Private to OEM
- Proprietary, mission-critical or sensitive data and workloads
- Dev environments

Source: SBD Automotive - Report 213 - Advanced Computing



SSP comprises high value modules with dedicated variants to address all Group vehicles

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Most automakers require multiple "stops" to SDV





Most OEMs can't make the jump "straight" to SDV – it's a more iterative engineering journey

Vehicle 1.0	Vehicle 2.0	Vehicle 3.0	Vehicle 4.0
Functional New feature? Let's add a new box	Digital Let's focus on digitizing our IVI	Updateable Let's keep the car fresh	Software-defined Let's fully decouple SW from HW
	STELLANTIS	Ford	
	RENAULT NISSAN MITSUBISHI	A LIMITED	5LFi ENG



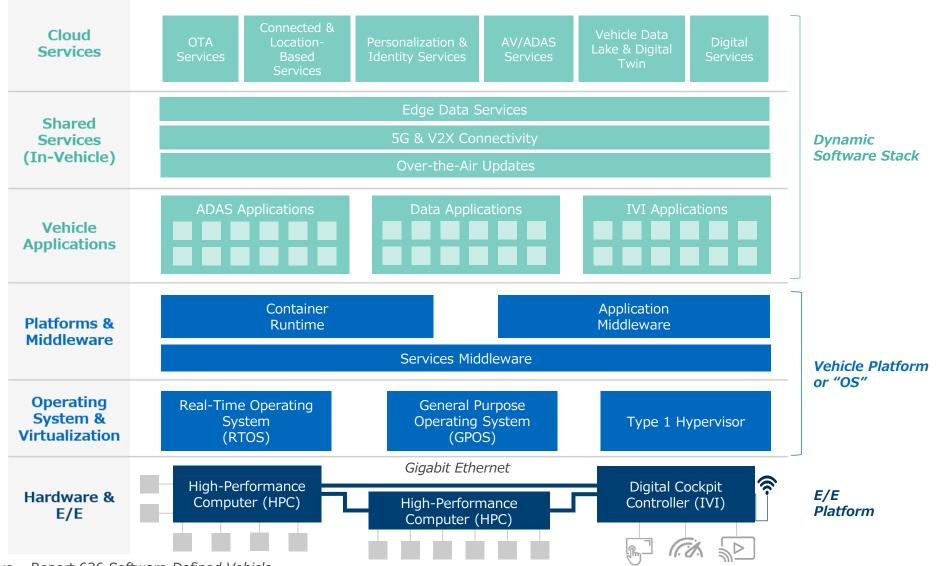
Challenges to OEMs

SDV architecture starts with abstraction from car to cloud



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Some OEMs pursue "Vehicle.OS" which hold most of software stack



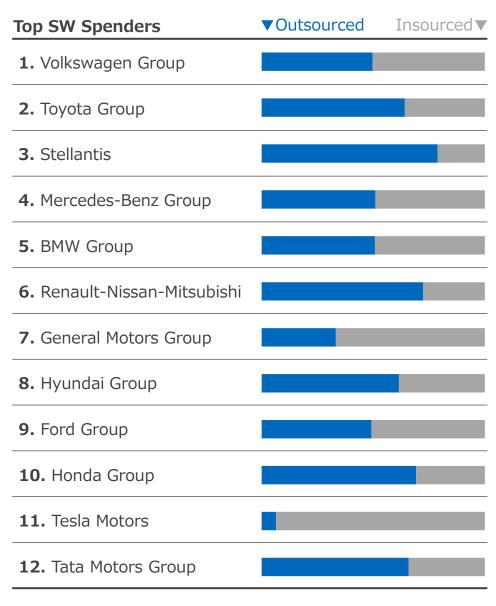
Key consideration: Build OR Buy?





Software sourcing strategies differ, limited by recruitment







Developer ecosystems, communities, and tools are the "secret sauce" to OEM-cloud partnership

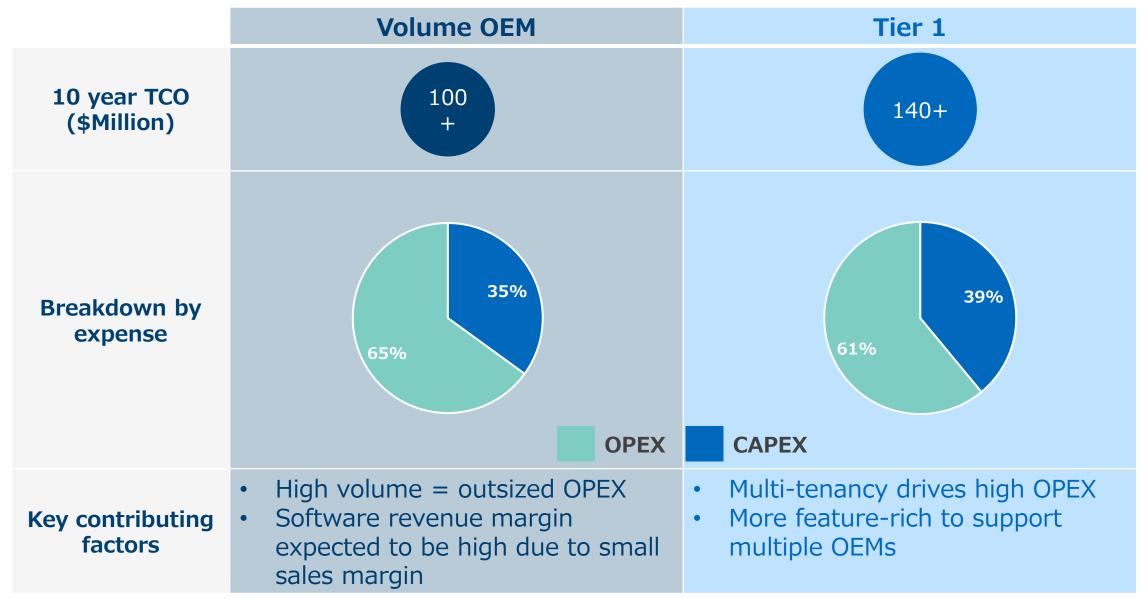
"Our #1 barrier to achieving greater in-house software development goals is recruitment."



Software Director at Major OEM

Hidden cost of SDV - OPEX of non-differentiating S/W





Whatever approach OEM take, everything cannot be under control

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	Integration Approach Leveraging 3 rd party software vendors	Long-Term Approach Careful investment for reduced risk	Fast Development Approach Immediate investment & re-organization
Cost	Low	Low	High
Time to Market	Fast	Slow	Fast
Intellectual Property Control	Poor	Strong	Strong









OSS as key accelerator

OSS as the engine of SDV

























OSS is not a panacea, but it will continue to grow in relevance



OSS is attractive to OEMs because:

- ✓ **Customization** for size/scale/context
- ✓ Access to development ecosystems, skillsets
- ✓ Lowering cost of development by:
 - ✓ Investing in mutually beneficial OSS
 - ✓ Eliminating licensing fees
- ✓ Reduction of **risk** via software supplier lockin
- ✓ Alignment with hardware/chipset architecture creates efficient optimization effort

But OEMs will still need licensed software because:

- Developing ASIL-C/D software is difficult and expensive
- Stricter regulations will create demand for complexity abstraction
- ✓ **Different components and domains** have different requirements
- ✓ Virtualization in mixed criticality environments remains a linchpin to SDVs
- ✓ Outsourcing management of upstream security threats & license compliance remains attractive

OEMs leveraging Tech Giants & OSS to accelerate transformation



Tech Giant Collaborations

Open Source SW Initiatives







Key effect of SDV adoption: bottom-up commodification



	Today	SDV Future		
	Mixed In-House/Outsourced Proprietary	In-House Proprietary/Ecosystem-Driven		
Cloud Services	WirelessCar Microsoft	aws Microsoft		
	Outsourced/Proprietary	In-House + Vendor Toolsets		
Vehicle Applications	⊜ BOSCH ontinental DENSO • APTIV•	OEM		
Container	Emerging Proprietary Solutions	OSS & OTA-Integrated Vendor Toolsets		
Runtime & Orchestration	BlackBerry DENSO NVIDIA.	SOAFEE planet **BlackBerry		
	Mixed	Standards-driven OSS & Vendor Toolsets		
Middleware		CycloneDDS AUTOSAR		
Operating	RTOS: Mixed GPOS: Primarily OSS	CycloneDDS AUTOWARE.AI OSS and/or container-driven IIIROS		
System	\\\\\\\\\\\\\\\\\\\\\\\\\\\\\\\\\\\\\\	AUT@SAR Red Hat		
	Droprioton (Mixed + Native Containers		
Hypervisors	*** BlackBerry Green Hills OPENSYNERGY	SOAFEE SOPENSYNERGY		

Different approaches take different tool / supplier relationships



	Integration Approach Leveraging 3 rd party software vendors	Long-Term Approach Careful investment for reduced risk	Fast Development Approach Immediate investment & re-organization
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Intellectual Property Control	Poor	Strong	Strong



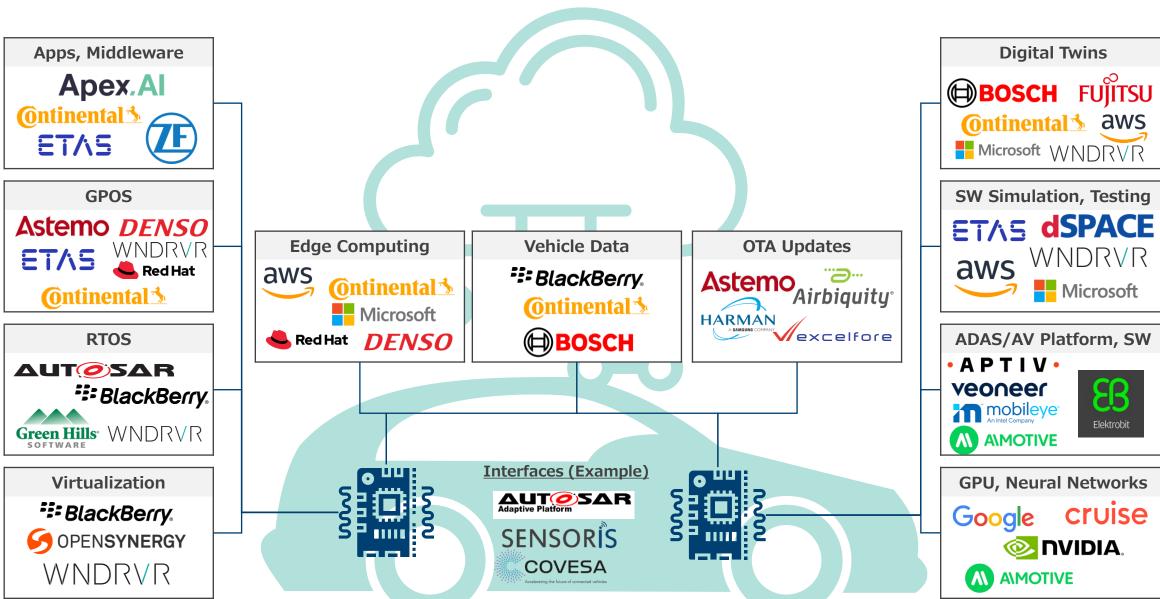




Integration Approach – Visualized



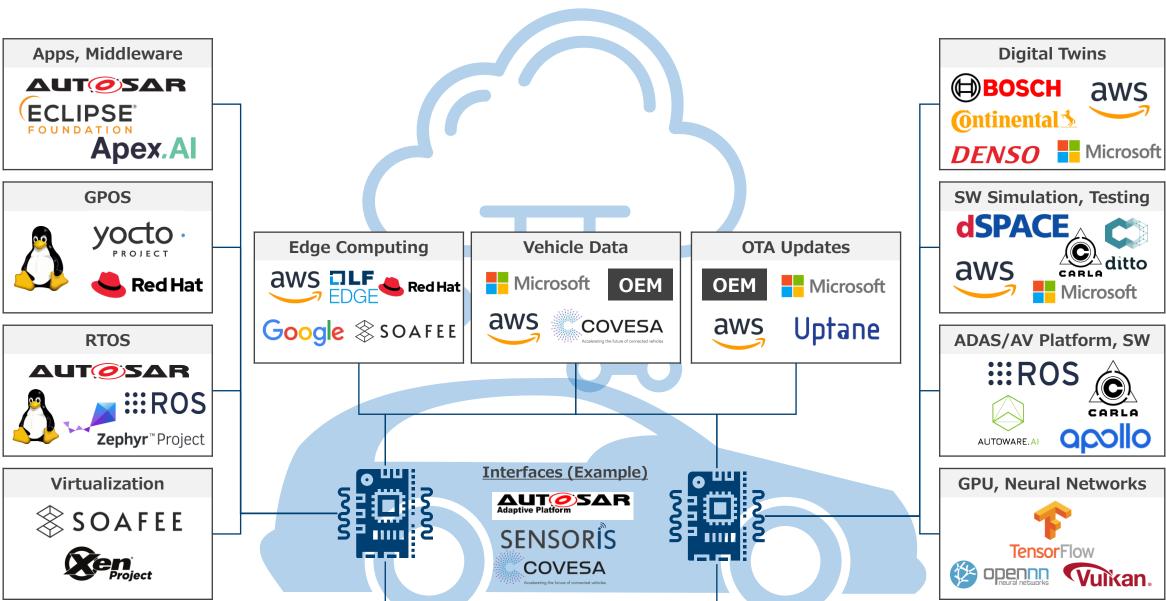




Long-Term Approach - Visualized

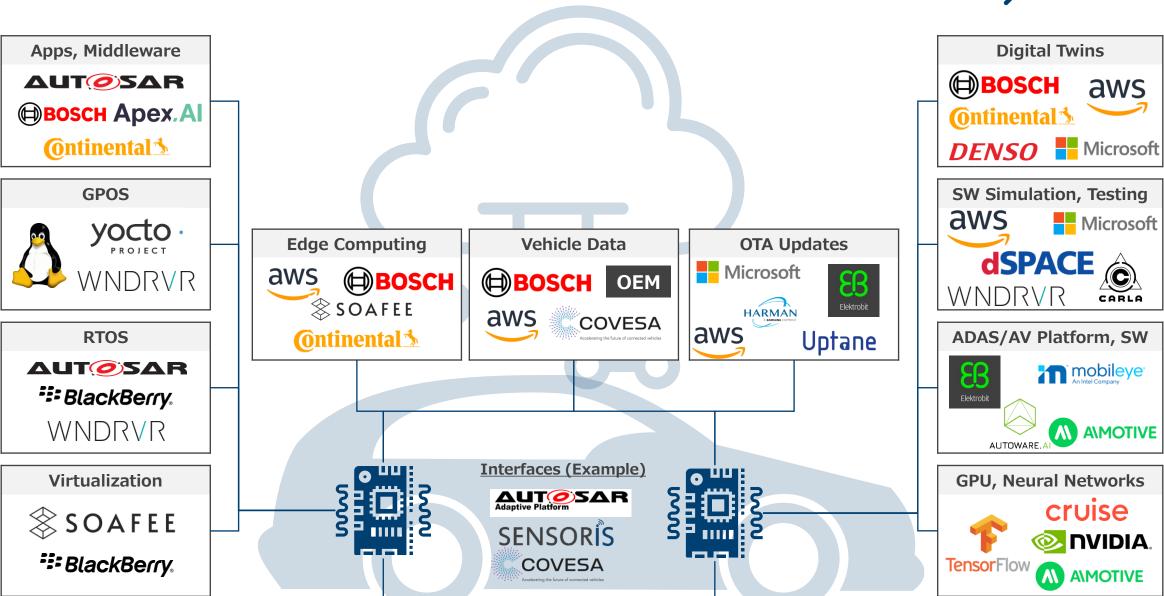






Fast Development Approach - Visualized





Final thoughts

SDV require overhaul of EE architecture and S/W architecture

Major challenge comes as a combination of organizational, technical and strategic challenges

Plenty of opportunities for OSS lie in SDV, but choice depends on OEMs' sourcing strategy



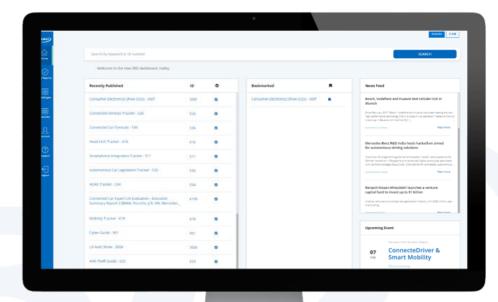


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